

General Description

The MAX4180 family of current-feedback amplifiers combines high-speed performance, low distortion, and excellent video specifications with ultra-low-power operation in miniature packages. They operate from ±2.25V to ±5.5V dual supplies, or from a single +5V supply. They require only 1mA of supply current per amplifier while delivering up to ±60mA of output current drive. The MAX4180/MAX4182/MAX4183/MAX4186 are compensated for applications with a closed-loop gain of +2 (6dB) or greater, and provide a -3dB bandwidth of 240MHz and a 0.1dB bandwidth of 70MHz. The MAX4181/MAX4184/MAX4185/MAX4187 are compensated for applications with a +1 (0dB) or greater gain, and provide a -3dB bandwidth of 270MHz and a 0.1dB bandwidth of 60MHz.

The MAX4180-MAX4187 feature 0.08%/0.03° differential gain and phase errors, a 20ns settling time to 0.1%, and a 450V/µs slew rate, making them ideal for highperformance video applications. The MAX4180/ MAX4181/MAX4183/MAX4185 have a low-power shutdown mode that reduces power-supply current to 135µA and places the outputs in a high-impedance state. This feature makes them ideal for multiplexing applications.

The single MAX4180/MAX4181 are offered in spacesaving 6-pin SOT23 packages.

Features

- ◆ Ultra-Low Supply Current: 1mA per Amplifier
- **♦ Shutdown Mode Outputs Placed in High-Z** Supply Current Reduced to 135µA
- ♦ Operate from a Single +5V Supply or Dual ±5V Supplies
- ♦ Wide Bandwidth 270MHz -3dB Small-Signal Bandwidth (MAX4181/MAX4184/MAX4185/MAX4187)
- ♦ 450V/µs Slew Rate
- ♦ Fast, 20ns Settling Time to 0.1%
- ♦ Excellent Video Specifications Gain Flatness to 70MHz (MAX4180/MAX4182/MAX4183/MAX4186) 0.08%/0.03° Differential Gain/Phase
- Low Distortion: -73dBc SFDR (fc = 5MHz, Vout = 2Vp-p)
- Available in Tiny Surface-Mount Packages 6-Pin SOT23 (MAX4180/MAX4181) 10-Pin µMAX (MAX4183/MAX4185) 16-Pin QSOP (MAX4186/MAX4187)

Applications

Portable/Battery-Powered Video/Multimedia Systems

Broadcast and High-Definition TV Systems

High-Speed A/D Buffers **CCD Imaging Systems**

Medical Imaging

High-Definition Surveillance Video

Professional Cameras

Video Switching/ Multiplexing

Ordering Information

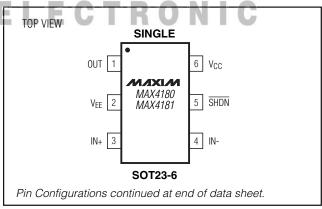
PART	TEMP RANGE	PIN- PACKAGE	TOP MARK
MAX4180EUT-T	-40°C to +85°C	6 SOT23-6	AAAB
MAX4180ESA	-40°C to +85°C	8 SO	_

Ordering Information continued at end of data sheet.

Selector Guide

PART	NO. OF AMPS	SHUTDOWN MODE	OPTIMIZED FOR
MAX4180	1	Yes	A _V ≥ 2
MAX4181	1	Yes	A _V ≥ 1
MAX4182	2	No	A _V ≥ 2
MAX4183	2	Yes	A _V ≥ 2
MAX4184	2	No	A _V ≥ 1
MAX4185	2	Yes	A _V ≥ 1
MAX4186	4	No	A _V ≥ 2
MAX4187	4	No	A _V ≥ 1

Pin Configurations



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Maxim Integrated Products 1

For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

ABSOLUTE MAXIMUM RATINGS

Supply Voltage (VCC to VEE)	12V
Analog Input Voltage	
Differential Input Voltage	
SHDN Input Voltage	
Short-Circuit Duration (OUT to GNE	
Continuous Power Dissipation (TA:	
6-Pin SOT23 (derate 7.10mW/°C	

8-Pin SO (derate 5.88mW/°C above +70°C)	471mW
10-Pin µMAX (derate 5.60mW/°C above +70°C)	444mW
14-Pin SO (derate 8.33mW/°C above +70°C)	667mW
16-Pin QSOP (derate 8.30mW/°C above +70°C)	667mW
Operating Temperature Range40°C	to +85°C
Storage Temperature Range65°C to	
Lead Temperature (soldering, 10s)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

DC ELECTRICAL CHARACTERISTICS—Dual Supplies

(V_{CC} = +5V, V_{EE} = -5V, V_{IN}+ = 0, SHDN ≥ 3V; T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Input Voltage Range	VcM	Guaranteed by CMRR test	±3.6	±3.9		V
Input Offset Voltage	Vos	$V_{CM} = 0$		±1.5	±7	mV
Input Offset-Voltage Drift	TC _{VOS}			±12		μV/°C
Input Offset-Voltage Matching		MAX4182-MAX4187		±1		mV
Input Bias Current (Positive Input)	I _{B+}			±1	±7	μΑ
Input Bias Current (Negative Input)	I _B .			±1	±12	μΑ
Input Resistance (Positive Input)	R _{IN+}	$-3.6V \le V_{IN+} \le 3.6V$, $-1V \le (V_{IN+} - V_{IN-}) \le 1V$	250	800		kΩ
Input Resistance (Negative Input)	R _{IN-}			160		Ω
Common-Mode Rejection Ratio	CMRR	-3.6V ≤ V _{CM} ≤ 3.6V	-50	-58		dB
Onen Lean Transveriatores	т_	$R_L = 1k\Omega$, $V_{OUT} = \pm 3.6V$	0.8	3.0		МΩ
Open-Loop Transresistance	T _R	$R_L = 150\Omega$, $V_{OUT} = \pm 2.5V$	0.3	0.9		IVISZ
		$R_L = 1k\Omega$	±3.75	±4.0		
Output Voltage Swing	V _{SW}	$R_L = 150\Omega$	±3.0	±3.3		V
		$R_L = 100\Omega$	RO	±3.0	C	
Output Current	IOUT	$R_L = 30\Omega$	±32	±60		mA
Output Short-Circuit Current	Isc			±80		mA
Output Resistance	Rout			0.2		Ω
Disabled Output Leakage Current	I _{OUT} (OFF)	SHDN ≤ V _{IL} , V _{OUT} ≤ ±3V (Notes 2, 4)		±0.1	±6.0	μΑ
SHDN Logic Low Threshold	V _I L	(Notes 3, 4)		,	√CC - 3.0	V
SHDN Logic High Threshold	VIH	(Notes 3, 4)	V _{CC} - 2.0			V

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DC ELECTRICAL CHARACTERISTICS—Dual Supplies (continued)

(V_{CC} = +5V, V_{EE} = -5V, V_{IN}+ = 0, SHDN ≥ 3V; T_A = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.) (Note 1)

PARAMETER	SYMBOL	COND	ITIONS	MIN	TYP	MAX	UNITS
SHDN Logic Input Bias Current	I _{IN}	V _{EE} ≤ SHDN ≤ V _{CC} (N	ote 4)		±0.1	±2.0	μΑ
Positive Power-Supply Rejection Ratio	PSRR+	VEE = -5V, VCC = 4.5V to 5.5V		60	71		dB
Negative Power-Supply Rejection Ratio	PSRR-	V _{CC} = 5V, V _{EE} = -4.5V to -5.5V		53	62		dB
Operating Supply Voltage	V _{CC} /V _{EE}			±2.25		±5.50	V
Quiescent Supply Current	Is	RL = ∞	MAX418_EUT		1.0	1.3	mA
per Amplifier	18	All other packages			1.0	1.2	IIIA
Shutdown Supply Current per Amplifier	IS(OFF)	SHDN = 0, R _L = ∞ (Note 4)			135	180	μА

DC ELECTRICAL CHARACTERISTICS—Single Supply

 $(V_{CC} = +5V, V_{EE} = 0, V_{IN} + = 2.5V, \overline{SHDN} \ge 3V, R_L \text{ to } V_{CC}/2; T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.}$ Typical values are at $T_A = +25^{\circ}C$.) (Note 1)

SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Vсм		1.3 to 3.7	1.1 to 3.9		V
Vos	V _{CM} = 2.5V		±1.5	±7	mV
TCvos			±12		μV/°C
	MAX4182-MAX4187		±1		mV
I _{B+}			±1	±7	μΑ
I _{B-}			±1	±12	μΑ
R _{IN+}	$1.3V \le V_{ N+} \le 3.7V$, $-1V \le (V_{ N+} - V_{ N-}) \le 1V$	250	800		kΩ
R _{IN} -	ELECT	RO	160	C	Ω
CMRR	1.3V ≤ V _{CM} ≤ 3.7V	-50	-58		dB
To	$R_L = 1k\Omega$, $V_{OUT} = 1.2V$ to 3.8V	0.8	2.5		MΩ
I 'K	$R_L = 150\Omega$, $V_{OUT} = 1.4V$ to 3.6V	0.275	0.9		10122
	$R_{\rm I} = 1k\Omega$	1.15 to	1.0 to		
V_{SW}	$R_L = 150\Omega$				V
		0.00			
	$R_L = 100\Omega$		3.7		
	VCM Vos TCVos IB+ IB- RIN+ RIN- CMRR TR	V _{CM} V _{OS} V _{CM} = 2.5V TC _{VOS} MAX4182-MAX4187 I _{B+} I _{B-} R _{IN+} 1.3V ≤ V _{IN+} ≤ 3.7V, -1V ≤ (V _{IN+} - V _{IN-}) ≤ 1V R _{IN-} CMRR 1.3V ≤ V _{CM} ≤ 3.7V T_R $R_L = 1k\Omega$, V _{OUT} = 1.2V to 3.8V $R_L = 150\Omega$, V _{OUT} = 1.4V to 3.6V $R_L = 1k\Omega$ V _{SW} $R_L = 150\Omega$	VCM 1.3 to 3.7 VOS VCM = 2.5V TCVOS MAX4182-MAX4187 IB+ IB- RIN+ 1.3V ≤ VIN+ ≤ 3.7V, -1V ≤ (VIN+ - VIN-) ≤ 1V 250 RIN- E CMRR 1.3V ≤ VCM ≤ 3.7V -50 TR RL = 1kΩ, VOUT = 1.2V to 3.8V RL = 150Ω, VOUT = 1.4V to 3.6V 0.275 RL = 1kΩ 1.15 to 3.85 VSW RL = 150Ω	V _{CM} $V_{OS} = V_{CM} = 2.5V$ $TC_{VOS} = \frac{1.3 \text{ to}}{3.7} = \frac{1.1 \text{ to}}{3.9}$ $MAX4182-MAX4187 = \pm 1$ $I_{B+} = \frac{1}{1}$ $I_{B+} = \frac{1.3V \le V_{IN+} \le 3.7V, -1V \le (V_{IN+} - V_{IN-}) \le 1V}{160}$ $E = \frac{1.3V \le V_{CM} \le 3.7V}{160}$ $T_{R} = \frac{1.3V \le V_{CM} \le 3.7V}{1.15 \text{ to}} = \frac{1.2V \text{ to } 3.8V}{3.6V}$ $R_{L} = 150Ω, V_{OUT} = 1.4V \text{ to } 3.6V$ $R_{L} = 150Ω$	V _{CM} $V_{CM} = 2.5V$ V_{CM



DC ELECTRICAL CHARACTERISTICS—Single Supply (continued)

 $(V_{CC} = +5V, V_{EE} = 0, V_{IN} + = 2.5V, \overline{SHDN} \ge 3V, R_L \text{ to } V_{CC}/2; T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}C.)$ (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Output Current	lout	$R_L = 30\Omega$	±18	±30		mA
Output Short-Circuit Current	I _{SC}			±50		mA
Output Resistance	Rout			0.2		Ω
Disabled Output Leakage Current	lout(off)	SHDN ≤ V _{IL} , 1.2V ≤ V _{OUT} ≤ 3.8V (Notes 2, 4)		±0.1	±4.0	μΑ
SHDN Logic-Low Threshold	V _{IL}	(Notes 3, 4)			V _{CC} - 3.0	V
SHDN Logic-High Threshold	VIH	(Notes 3, 4)	V _{CC} - 2.0			V
SHDN Logic Input Bias Current	I _{IN}	0 ≤ SHDN ≤ V _{CC} (Note 4)		±0.1	±2.0	μΑ
Power-Supply Rejection Ratio	PSRR	V _{CC} = 4.5V to 5.5V	60	71		dB
Operating Supply Voltage	Vcc		4.5		5.5	V
Quiescent Supply Current	Is	R _L = ∞		1.0	1.25	mA
per Amplifier	15	All other packages		1.0	1.2	111/4
Shutdown Supply Current per Amplifier	I _{S(OFF)}	SHDN = 0, R _L = ∞ (Note 4)		135	180	μΑ

AC ELECTRICAL CHARACTERISTICS—Dual Supplies (MAX4180/4182/4183/4186)

 $(V_{CC} = +5V, V_{EE} = -5V, V_{IN} = 0, \overline{SHDN} \ge 3V, A_{V} = +2V/V;$ see Table 1 for RF and RG values; $T_{A} = +25^{\circ}C$, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITION	S	MIN	TYP	MAX	UNITS	
Small-Signal -3dB Bandwidth	D\\/	O Fall modified	R _L =1kΩ	180	245		N 41 1-	
(Note 5)	BW _{SS}	<0.5dB peaking $R_L=150\Omega$			190		MHz	
Large-Signal -3dB Bandwidth	BWLS	$V_{OUT} = 2V_{p-p}, R_{L} = 1k\Omega$			150	_	MHz	
Bandwidth for 0.1dB Flatness	BW _{0.1dB}	$R_L = 1k\Omega$		30	70		MHz	
(Note 5)	DVV0.1dB	$R_L = 150\Omega$			70		TVII IZ	
Slew Rate (Note 5)	SR	Vout = $2V$ step, $R_L = 1k\Omega$	Rising edge	340	450		V/µs	
Siew hate (Note 5)	SIT	VOOT = 2V Step, Tit = TK\$2	Falling edge	315	420		ν/μS	
Settling Time to 0.1%	ts	Vout = $2V$ step, $R_L = 1k\Omega$	ECT	RO	20	6	ns	
Rise/Fall Time	t _R , t _F	$V_{OUT} = 2V \text{ step}, R_L = 1k\Omega$			5		ns	
Spurious-Free Dynamic Range	SFDR	f _C = 5MHz, V _{OUT} = 2Vp-p	$R_L = 1k\Omega$		73		dBc	
Spurious-i ree Dynamic Hange	JI DIT	10 - SIVII 12, VOUT - ZVP-P	$R_L = 150\Omega$		57		ubc	
Second Harmonic Distortion		f _C = 5MHz, V _{OUT} = 2Vp-p	$R_L = 1k\Omega$		-83		dBc	
Second Harmonic Distortion		10 - SIVII 12, VOUI - ZVP-P	$R_L = 150\Omega$		-68		ubc	
Third Harmonic Distortion		f _C = 5MHz, V _{OUT} = 2Vp-p	$R_L = 1k\Omega$		-73		dBc	
THIRD HAITHORIC DISTORTION	IC = SMHZ, VOUT = 2VP		$R_L = 150\Omega$		-57			

AC ELECTRICAL CHARACTERISTICS—Dual Supplies (MAX4180/4182/4183/4186) (cont.)

 $(V_{CC} = +5V, V_{EE} = -5V, V_{IN} = 0, \overline{SHDN} \ge 3V, A_V = +2V/V;$ see Table 1 for R_F and R_G values; T_A = +25°C, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITION	S	MIN TYP	MAX	UNITS	
Differential Phase Error	DP	NTSC	$R_L = 1k\Omega$	0.03		degrees	
Differential Fridge Error	Di	11100	$R_L = 150\Omega$			degrees	
Differential Gain Error	DG	NTSC	$R_L = 1k\Omega$	0.08		%	
Billiorofittal daili Effor	DG	11100	$R_L = 150\Omega$	0.01		,,,	
Input Noise-Voltage Density	en	f = 10kHz		2		nV/√Hz	
Input Noise-Current Density	in	f = 10kHz	IN+	4		pA/√ Hz	
input voice current Beneity	"11	1 – 10K/12		1 - 10N12 IN- 5			pr (11 12
Input Capacitance (Positive Input)	C _{IN+}			1.5		pF	
Output Impedance	Z _{OUT}	f = 10kHz		4.8		Ω	
Disabled Output Capacitance	Cout(off)	SHDN ≤ V _{IL} , V _{OUT} ≤ ±3V (No	otes 2, 4)	4		рF	
Turn-On Time from SHDN	ton	(Note 4)		40		ns	
Turn-Off Time to SHDN	toff	(Note 4)		400		ns	
Power-Up Time				200		μs	
Off-Isolation		$\overline{\text{SHDN}} \le 2\text{V}, \text{R}_{\text{L}} = 150\Omega, \text{f} = 1$	10MHz	-60		dB	
Crosstalk		f = 10MHz, MAX4182/4183/4186		-60		dB	
Gain Matching to 0.1dB		f = 10MHz, MAX4182/4183/4	1186	25		MHz	

AC ELECTRICAL CHARACTERISTICS—Dual Supplies (MAX4181/4184/4185/4187)

 $(V_{CC} = +5V, V_{EE} = -5V, V_{IN+} = 0, SHDN \ge 3V, A_V = +1V/V;$ see Table 1 for R_F values; $T_A = +25^{\circ}C$, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITION	S	MIN	TYP	MAX	UNITS
Small-Signal -3dB Bandwidth (Note 5)	BW _{SS}	<0.5dB peaking	$R_{L} = 1k\Omega$ $R_{L} = 150\Omega$	195	270 205		MHz
Large-Signal -3dB Bandwidth	BWLS	$V_{OUT} = 2V_{p-p}, R_{L} = 1k\Omega$			90		MHz
Bandwidth for 0.1dB Flatness (Note 5)	BW _{0.1dB}	$R_{L} = 1k\Omega$ $R_{L} = 150\Omega$		20	60 55		MHz
Slew Rate (Note 5)	SR	$V_{OUT} = 2V$ step, $R_L = 1k\Omega$	Rising edge Falling edge	250 200	320 265	C	V/µs
Settling Time to 0.1%	ts	$V_{OUT} = 2V \text{ step}, R_L = 1k\Omega$			21		ns
Rise/Fall Time	t _R and t _F	$V_{OUT} = 2V$ step, $R_L = 1k\Omega$			5		ns
Spurious-Free Dynamic Range	SFDR	f _C = 5MHz, V _{OUT} = 2Vp-p	$R_L = 1k\Omega$		57		dB
Spundus-Free Dynamic Hange	OI DIT	10 - 31VII 12, VOOT - 2VP-P	$R_L = 150\Omega$		66		QD
Second Harmonic Distortion		f _C = 5MHz, V _{OUT} = 2Vp-p	$R_L = 1k\Omega$		-70		dB
Second Harmonic Distortion		10 - 31VII 12, VOOT - 2VP-P	$R_L = 150\Omega$		-73		l GD
Third Harmonic Distortion		$f_C = 5MHz$, $V_{OUT} = 2Vp-p$	$R_L = 1k\Omega$		-57		dB
THIRD HATHOUTE DISTORTION			$R_L = 150\Omega$		-66		
Differential Phase Error	DP	DP NTSC			0.01		degrees
Differential Friase LITO	וט	INTOC	$R_L = 150\Omega$		0.48		uegrees

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AC ELECTRICAL CHARACTERISTICS—Dual Supplies (MAX4181/4184/4185/4187) (cont.)

 $(V_{CC} = +5V, V_{EE} = -5V, V_{IN+} = 0, \overline{SHDN} \ge 3V, A_V = +1V/V$; see Table 1 for R_F values; T_A = +25°C, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITION	S	MIN	TYP	MAX	UNITS
Differential Gain Error	DG	NTSC	$R_L = 1k\Omega$		0.09		%
Differential dain Error	Da	11130	$R_L = 150\Omega$		0.16		76
Input Noise-Voltage Density	en	f = 10kHz			2		nV/√Hz
Input Noise-Current Density	in	f = 10kHz	IN+		4		pA/√Hz
			IN-		5		
Input Capacitance (Positive Input)	C _{IN+}				1.5		рF
Output Impedance	Zout	f = 10kHz		7	4.8		Ω
Disabled Output Capacitance	Cout(off)	SHDN ≤ V _{IL} , V _{OUT} ≤ ±3V (No	otes 2, 4)		4		pF
Turn-On Time from SHDN	ton	(Note 4)			50		ns
Turn-Off Time to SHDN	toff	(Note 4)			400		ns
Power-Up Time					200		μs
Off-Isolation		$\overline{\text{SHDN}} \le 2\text{V}, \text{R}_{\text{L}} = 150\Omega, \text{f} = 10\text{MHz}$			-54		dB
Crosstalk		f = 10MHz, MAX4184/MAX4185/MAX4187			-60		dB
Gain Matching to 0.1dB		f = 10MHz, MAX4184/MAX4	185/MAX4187	7	25		MHz

AC ELECTRICAL CHARACTERISTICS—Single Supply (MAX4180/4182/4183/4186)

 $(V_{CC} = +5V, V_{EE} = 0, V_{IN} + = 2.5V, \overline{SHDN} \ge 3V, A_V = +2V/V;$ see Table 1 for R_F and R_G values; $T_A = +25^{\circ}C$, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITION	CONDITIONS			MAX	UNITS	
Small-Signal -3dB Bandwidth	BWss	<0.5dB peaking	$R_L = 1k\Omega$	155	210		MHz	
(Note 5)	DW55	Co.odb peaking	$R_L = 150\Omega$		165		IVII IZ	
Large-Signal -3dB Bandwidth	BWLS	$V_{OUT} = 2V_{p-p}, R_L = 1k\Omega$			110		MHz	
Bandwidth for 0.1dB Flatness	BW _{0.1dB}	$R_L = 1k\Omega$		20	50		MHz	
(Note 5)	DVV0.10B	$R_L = 150\Omega$			40		IVII IZ	
Slew Rate (Note 5)	SR	$V_{OUT} = 2V \text{ step}, R_L = 1k\Omega$	Rising edge	260	340		V/uc	
Siew Mate (Note 3)	Sh	VOOT - 2V Step, TIL - TK22	Falling edge	220	300	G	- V/µs	
Settling Time to 0.1%	ts	$V_{OUT} = 2V \text{ step}, R_L = 1k\Omega$			20		ns	
Rise/Fall Time	t _R and t _F	$V_{OUT} = 2V \text{ step, } R_L = 1k\Omega$			6		ns	
Spurious-Free Dynamic Range	SFDR	f _C = 5MHz, V _{OUT} = 2Vp-p	$R_L = 1k\Omega$		72		dB	
Spurious-i ree Dynamic Hange	JI DIN	10 - SIVII 12, VOUT - ZVP-P	$R_L = 150\Omega$		57		- ub	
Second Harmonic Distortion		f _C = 5MHz, V _{OUT} = 2Vp-p	$R_L = 1k\Omega$		-80		dBc	
Second Harmonic Distortion		10 - SIVII 12, VOUT - ZVP-P	$R_L = 150\Omega$		-76		- ubc	
Third Harmonic Distortion		f _C = 5MHz, V _{OUT} = 2Vp-p	$R_L = 1k\Omega$		-72		dBc	
Third Hairhorlic Distortion		10 - SIVII 12, VOUT - ZVP-P	$R_L = 150\Omega$		-57		ubc	
Differential Phase Error	DP	NTSC	$R_L = 1k\Omega$		0.01		degrees	
Differential Friase Effor		11100	$R_L = 150\Omega$		0.35			

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AC ELECTRICAL CHARACTERISTICS—Single Supply (MAX4180/4182/4183/4186) (cont.)

(V_{CC} = +5V, V_{EE} = 0, V_{IN}+ = 2.5V, SHDN ≥ 3V, A_V = +2V/V; see Table 1 for R_F and R_G values; T_A = +25°C, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITION	MIN	TYP	MAX	UNITS	
Differential Gain Error	DG	NTSC	R _L = 1kΩ		0.10		%
Differential Gain Error	DG	NISC	R _L = 150Ω		0.03		70
Input Noise-Voltage Density	en	f = 10kHz			2		nV/√Hz
Input Noise-Current Density		f _ 10kUz	IN+		4		pA/√Hz
input Noise-Current Density	İn	f = 10kHz			5		PAVITZ
Input Capacitance (Positive Input)	C _{IN+}				1.5		pF
Output Impedance	Zout	f = 10kHz		47	4.8		Ω
Disabled Output Capacitance	Cout(OFF)	$\overline{SHDN} \le V_{IL}$, $1.2V \le V_{OUT} \le 3$	3.8V (Notes 2, 4)	7	4		pF
Turn-On Time from SHDN	ton	(Note 4)			40		ns
Turn-Off Time to SHDN	toff	(Note 4)	- 1		400		ns
Power-Up Time					200		μs
Off-Isolation		$\overline{SHDN} \le 2V$, $R_L = 150\Omega$, $f = 1$	10MHz		-60		dB
Crosstalk		f = 10MHz, MAX4182/MAX4		-60	2010	dB	
Gain Matching to 0.1dB		f = 10MHz, MAX4182/MAX4	183/ <mark>MAX4186</mark>		25		MHz

AC ELECTRICAL CHARACTERISTICS—Single Supply (MAX4181/4184/4185/4187)

 $(V_{CC} = +5V, V_{EE} = 0, V_{IN} + = 2.5V, \overline{SHDN} \ge 3V, A_V = +1V/V;$ see Table 1 for RF values; $T_A = +25$ °C, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITION	MIN	TYP	MAX	UNITS	
Small-Signal -3dB Bandwidth (Note 5)	BWss	<0.5dB peaking	$R_L = 1k\Omega$ $R_L = 150\Omega$	175	220 170		MHz
Large-Signal -3dB Bandwidth	BWLS	$V_{OUT} = 2V_{p-p}, R_{L} = 1k\Omega$	1.12		110		MHz
Bandwidth for 0.1dB Flatness (Note 5)	BW _{0.1dB}	$R_{L} = 1k\Omega$ $R_{L} = 150\Omega$		16	40 30		MHz
Slew Rate (Note 5)	SR	$V_{OUT} = 2V$ step, $R_L = 1k\Omega$	Rising edge Falling edge	210 170	275 215		V/µs
Settling Time to 0.1%	ts	$V_{OUT} = 2V$ step, $R_L = 1k\Omega$			22		ns
Rise/Fall Time	t _R and t _F	$V_{OUT} = 2V$ step, $R_L = 1k\Omega$	ECHI	R0	7	C	ns
Spurious-Free Dynamic Range	SFDR	$f_C = 5MHz$, $V_{OUT} = 2Vp-p$	$R_{L} = 1k\Omega$ $R_{L} = 150\Omega$		55 59		dB
Second Harmonic Distortion		$f_C = 5MHz$, $V_{OUT} = 2Vp-p$	$R_{L} = 1k\Omega$ $R_{L} = 150\Omega$		-61 -72		dBc
Third Harmonic Distortion		f _C = 5MHz, V _{OUT} = 2Vp-p	$R_{L} = 1k\Omega$ $R_{L} = 150\Omega$		-55 -59		dBc
Differential Phase Error	DP	NTSC	$R_{L} = 1k\Omega$ $R_{L} = 150\Omega$		0.01 0.35		degrees



AC ELECTRICAL CHARACTERISTICS—Single Supply (MAX4181/4184/4185/4187) (cont.)

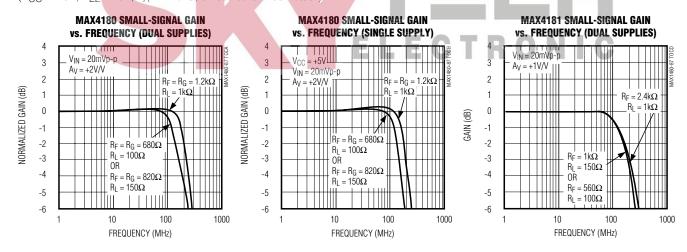
 $(V_{CC} = +5V, V_{EE} = 0, V_{IN} + = 2.5V, \overline{SHDN} \ge 3V, A_V = +1V/V$; see Table 1 for R_F values; T_A = +25°C, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS		MIN TYP	MAX	UNITS
Differential Gain Error	DG	NTSC	R _L = 1kΩ	0.10		%
Differential Gain Enoi	DG	NISC	R _L = 150Ω	0.03		/^
Input Noise-Voltage Density	e _n	f = 10kHz		2		nV/√Hz
Input Noise-Current Density	İn	f = 10kHz	IN+	4		pA/√Hz
impatriolog danielit delibity	-11		IN-	5		p, , , ,
Input Capacitance (Positive Input)	C _{IN+}			1.5		рF
Output Impedance	Zout	f = 10kHz		4.8		Ω
Disabled Output Capacitance	Cout(off)	$\overline{SHDN} \le V_{IL}$, $1.2V \le V_{OUT} \le 1.2V$	3.8V (Notes 2, 4)	4		pF
Turn-On Time from SHDN	ton	(Note 4)		40		ns
Turn-Off Time to SHDN	toff	(Note 4)		400		ns
Power-Up Time				200		μs
Off-Isolation		$\overline{SHDN} \le 2V$, $R_L = 150\Omega$, $f =$	10MHz	-54		dB
Crosstalk		f = 10MHz, MAX4184/MAX4	-60		dB	
Gain Matching to 0.1dB		f = 10MHz, MAX4184/MAX4	185/MAX4187	25		MHz

- Note 1: The MAX418_EUT is 100% production tested at T_A = +25°C. Specifications over temperature limits are guaranteed by design.
- Note 2: Does not include current into the external-feedback network.
- Note 3: Over operating supply-voltage range.
- Note 4: Specification applies to MAX4180/MAX4181/MAX4183 and MAX4185.
- Note 5: The AC specifications shown are not measured in a production test environment. The minimum AC specifications given are based on the combination of worst-case design simulations along with a sample characterization of units. These minimum specifications are for design guidance only and are not intended to guarantee AC performance (see AC Testing/Performance). For 100% testing of those parameters, contact the factory.

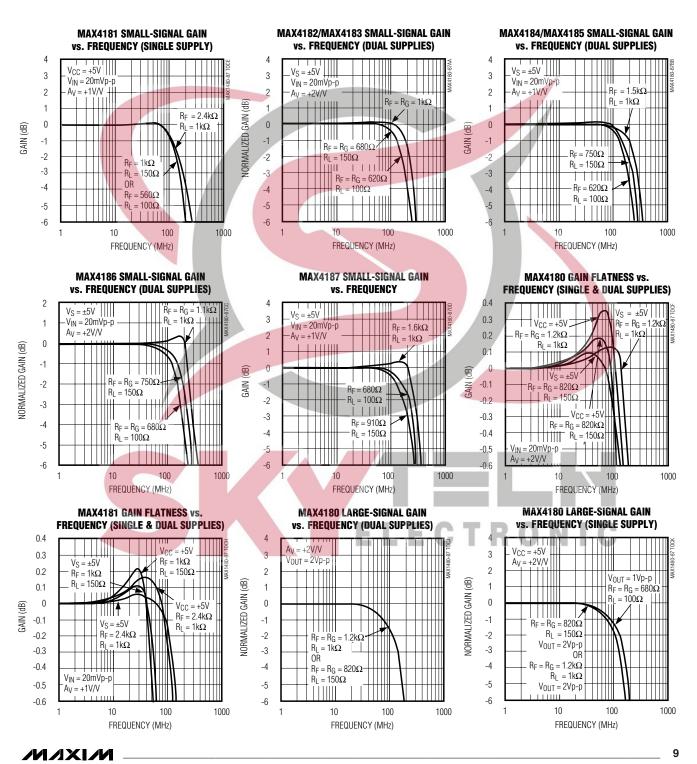
Typical Operating Characteristics

 $(V_{CC} = +5V, V_{EE} = -5V, T_A = +25^{\circ}C, unless otherwise noted.)$



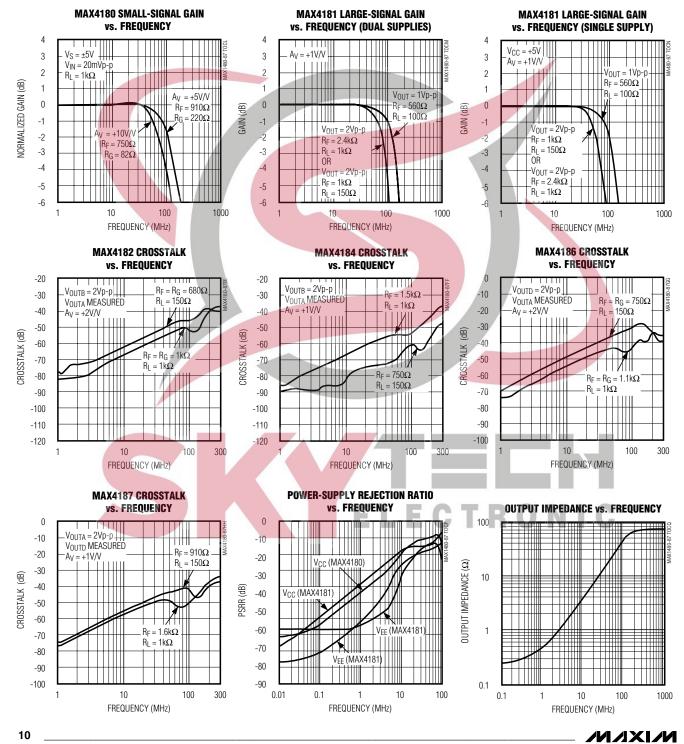
Typical Operating Characteristics (continued)

($V_{CC} = +5V$, $V_{EE} = -5V$, $T_A = +25$ °C, unless otherwise noted.)



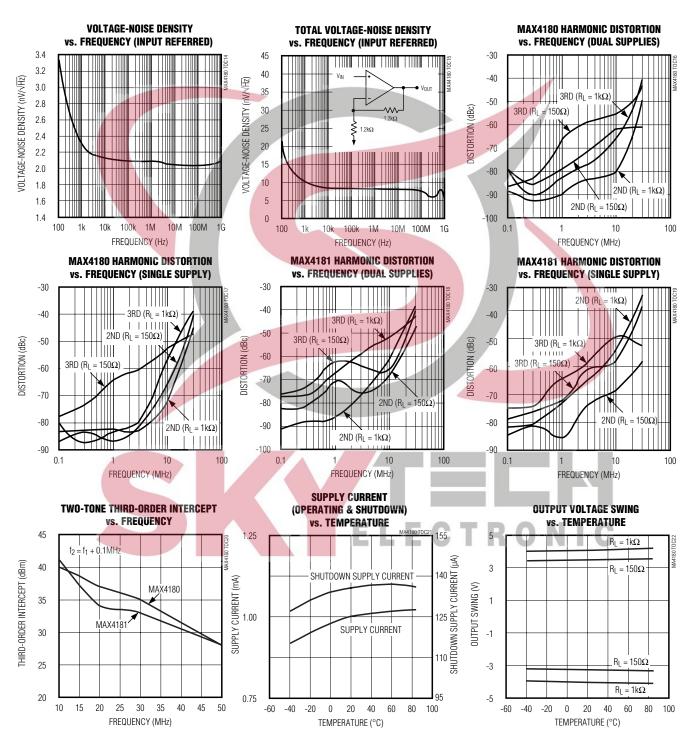
Typical Operating Characteristics (continued)

($V_{CC} = +5V$, $V_{EE} = -5V$, $T_A = +25$ °C, unless otherwise noted.)



Typical Operating Characteristics (continued)

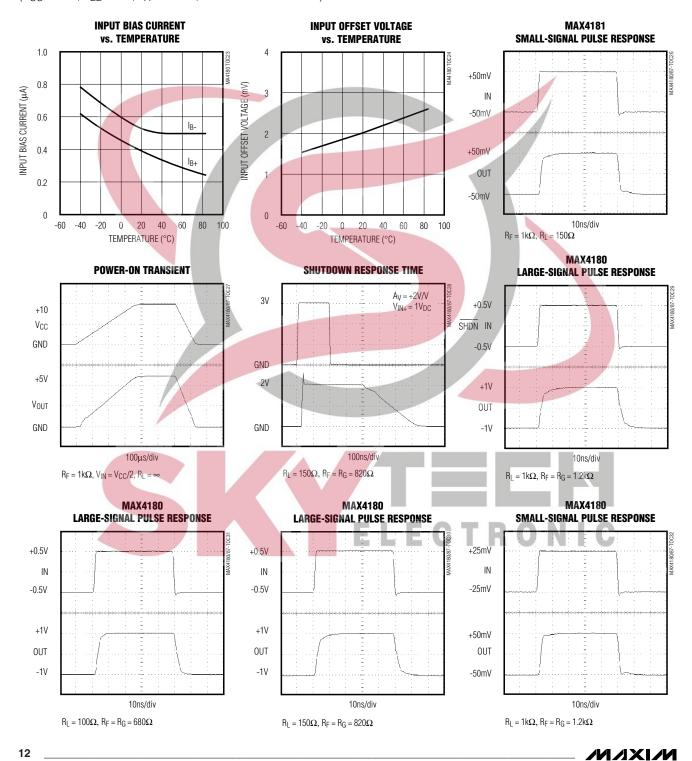
($V_{CC} = +5V$, $V_{EE} = -5V$, $T_A = +25$ °C, unless otherwise noted.)



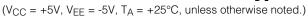
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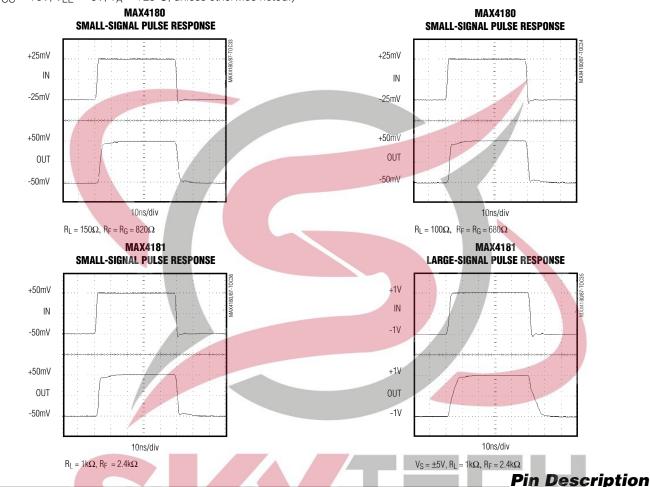
_Typical Operating Characteristics (continued)

($V_{CC} = +5V$, $V_{EE} = -5V$, $T_A = +25$ °C, unless otherwise noted.)



Typical Operating Characteristics (continued)





MAX4180/MAX4181

	PIN MAX4180/MAX4181		ELECTRONIC
so	SOT23-6		
1, 5	_	N.C.	No Connection. Not internally connected.
2	4	IN-	Inverting Input
3	3	IN+	Noninverting Input
4	2	VEE	Negative Power Supply. Connect V _{EE} to -5V or ground for single-supply operation.
6	1	OUT	Amplifier Output
7	6	Vcc	Positive Power Supply. Connect V _{CC} to +5V.
8	5	SHDN	Shutdown Input. Device is enabled when $\overline{SHDN} \ge (V_{CC} - 2V)$ and disabled when $\overline{SHDN} \le (V_{CC} - 3V)$.

Pin Description (continued)

MAX4182/MAX4183/MAX4184/MAX4185

	PIN			
MAX4182 MAX4184	MAX4183 MAX4185	MAX4183 MAX4185	NAME	FUNCTION
SO	so	μМΑХ		
1	1	1	OUTA	Amplifier A Output
2	2	2	INA-	Amplifier A Inverting Input
3	3	3	INA+	Amplifier A Noninverting Input
4	4	4	VEE	Negative Power Supply. Connect V _{EE} to -5V or ground for single-supply operation.
_	5, 7, 8, 10	-/-	N.C.	No Connection. Not internally connected.
_	6	5	SHDNA	Shutdown Control Input for Amplifier A. Amplifier A is enabled when $\overline{SHDNA} \ge (V_{CC} - 2V)$ and disabled when $\overline{SHDNA} \le (V_{CC} - 3V)$.
_	9	6	SHDNB	Shutdown Control Input for Amplifier B. Amplifier B is enabled when SHDNB ≥ (V _{CC} - 2V) and disabled when SHDNB ≤ (V _{CC} - 3V).
5	11	7	INB+	Amplifier B Noninverting Input
6	12	8	INB-	Amplifier B Inverting Input
7	13	9	OUTB	Amplifier B Output
8	14	10	Vcc	Positive Power Supply. Connect V _{CC} to +5V.

MAX4186/MAX4187

P	IN			
MAX4186 MAX4187	MAX4186 MAX4187	NAME	FUNCTION	
SO	QSOP			
1	1	OUTA	Amplifier A Output	
2	2	INA-	Amplifier A Inverting Input	
3	3	INA+	Amplifier A Noninverting Input	
4	4	Vcc	Positive Power Supply. Connect V _{CC} to +5V.	
5	5	INB+	Amplifier B Noninverting Input	
6	6	INB-	Amplifier B Inverting Input	
7	7	OUTB	Amplifier B Output	
_	8, 9	N.C.	No Connection. Not internally connected.	
8	10	OUTC	Amplifier C Output	
9	11	INC-	Amplifier C Inverting Input	
10	12	INC+	Amplifier C Noninverting Input	
11	13	V _{EE}	Negative Power Supply. Connect V _{EE} to -5V or ground for single-supply operation.	
12	14	IND+	Amplifier D Noninverting Input	
13	15	IND-	Amplifier D Inverting Input	
14	16	OUTD	Amplifier D Output	

Detailed Description

The MAX4180–MAX4187 are ultra-low-power current-feedback amplifiers featuring bandwidths up to 270MHz, 0.1dB gain flatness to 90MHz, and low differential gain (0.08%) and phase (0.03°) errors. These amplifiers achieve ultra-high bandwidth-to-power ratios with low distortion, wide signal swing, and excellent load-driving capabilities. They are optimized for $\pm 5 \rm V$ supplies but also operate from a single $\pm 5 \rm V$ supply while consuming only 1mA per amplifier. With $\pm 60 \rm mA$ output current drive capability, the devices achieve low distortion even while driving 150 Ω loads.

Wide bandwidth, low power, low differential phase and gain error, and excellent gain flatness make the MAX4180–MAX4187 ideal for use in portable video equipment such as cameras, video switchers, and other battery-powered applications. Their two-stage design provides higher gain and lower distortion than conventional single-stage, current-feedback topologies. This feature, combined with fast settling time, makes these devices suitable for buffering high-speed analog-to-digital converters (ADCs).

The MAX4180/MAX4181/MAX4183/MAX4185 have a low-power shutdown mode that is activated by driving the amplifiers' SHDN input low. Placing them in shutdown reduces quiescent supply current to 135µA (typ) and places amplifier outputs in a high-impedance state. These amplifiers can be used to implement a high-speed multiplexer by connecting together the outputs of multiple amplifiers and controlling the SHDN inputs to enable one amplifier and disable all the others. The disabled amplifiers present very little load (0.1µA leakage current and 4pF capacitance) to the active amplifiers' output. Note that the feedback network impedance of all the disabled amplifiers must be considered when calculating the total load on the active amplifier output.

Application Information

Theory of Operation

The MAX4180–MAX4187 are current-feedback amplifiers, and their open-loop transfer function is expressed as a transimpedance, $\Delta V_{OUT}/\Delta I_{IN},$ or $T_Z.$ The frequency behavior of the open-loop transimpedance is similar to the open-loop gain of a voltage-mode feedback amplifier. That is, it has a large DC value and decreases at approximately 6dB per octave.

Analyzing the follower with gain, as shown in Figure 1, yields the following transfer function:

 $V_{OUT} / V_{IN} = G \times [(T_Z(S) / T_Z(s) + G \times (R_{IN} + R_F))]$

where G = Avcl = 1 + (R_F / R_G), and R_{IN} = 1/g_M \cong 160 Ω . At low gains, G x R_{IN} < R_F. Therefore, the closed-loop bandwidth is essentially independent of closed-loop gain. Similarly, T_Z > R_F at low frequencies, so that:

$$\frac{V_{OUT}}{V_{IN}} = G = 1 + (R_F / R_G)$$

Layout and Power-Supply Bypassing

The MAX4180–MAX4187 have an RF bandwidth and, consequently, require careful board layout, including the possible use of constant-impedance microstrip or stripline techniques.

To realize the full AC performance of these high-speed amplifiers, pay careful attention to power-supply bypassing and board layout. The PC board should have at least two layers: a signal and power layer on one side, and a large, low-impedance ground plane on the other side. The ground plane should be as free of voids as possible. With multilayer boards, locate the ground plane on a layer that incorporates no signal or power traces.

Regardless of whether a constant-impedance board is used, observe the following guidelines when designing the board:

- Do not use wire-wrap boards. They are too inductive.
- Do not use breadboards. They are too capacitive.
- Do not use IC sockets. They increase parasitic capacitance and inductance.
- Use surface-mount components rather than throughhole components. They give better high-frequency performance, have shorter leads, and have lower parasitic reactances.

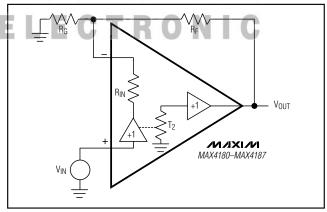


Figure 1. Current-Feedback Amplifier

- Keep lines as short and as straight as possible.
- Do not make 90° turns; round all corners.
- Observe high-frequency bypassing techniques to maintain the amplifiers' accuracy. The bypass capacitors should include a 0.01µF to 0.1µF ceramic capacitor between each supply pin and the ground plane, located as close to the package as possible.
- Place a 1µF ceramic capacitor in parallel with each 0.01µF to 0.1µF capacitor as close to them as possible.
- Place a 10µF to 15µF low-ESR tantalum at the point of entry to the power-supply pins' PC board. The power-supply trace should lead directly from the tantalum capacitor to the VCC and VEE pins.
- Keep PC traces short and use surface-mount components to minimize parasitic inductance.

Maxim's High-Speed Evaluation Board

Figures 2 and 3 show layouts of Maxim's high-speed single SOT23 and SO evaluation boards. These boards were developed using the techniques described above. The smallest available surface-mount resistors were used for feedback and back-termination to minimize their distance from the part, reducing the capacitance associated with longer lead lengths.

SMA connectors were used for best high-frequency performance. Because distances are extremely short, performance is unaffected by the fact that inputs and outputs do not match a 50Ω line. However, in applications that require lead lengths greater than one-quarter of the wavelength of the highest frequency of interest, use constant-impedance traces.

Fully assembled evaluation boards are available for the MAX4180ESA.

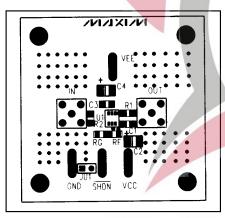


Figure 2a. SOT23 High-Speed EV Board Component Placement Guide— Component Side

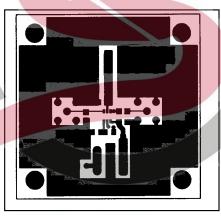


Figure 2b. SOT23 High-Speed EV Board Layout—Component Side

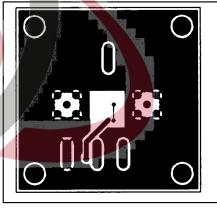


Figure 2c. High-Speed EV Board Layout— Solder Side

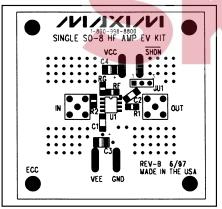


Figure 3a. SO-8 High-Speed EV Board Component Placement Guide— Component Side

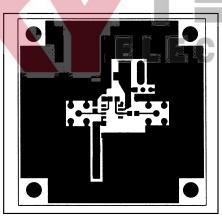


Figure 3b. SO-8 High-Speed EV Board Layout—Component Side

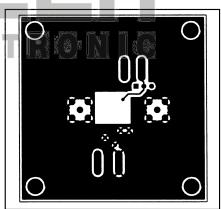


Figure 3c. SO-8 High-Speed EV Board Layout—Solder Side

Table 1. Recommended Component Values

			MAX4	MAX4181				
COMPONENT/BW	A _V = +2V/V		A _V = +5V/V	A _V = +10V/V				
	$R_L = 1k\Omega$	R _L = 150 Ω	R _L = 100Ω	R_L = 1kΩ/150Ω	R _L = 1kΩ/150Ω	$R_L = 1k\Omega$ $R_L = 150\Omega$		R _L = 100Ω
$R_F\left(\Omega\right)$	1.2k	820	680	520	560	2.4k	1k	560
R _G (Ω)	1.2k	820	680	130	56	-//	_	_
-3dB BW (MHz)	245	190	190	120	76	270	205	200

	MAX	1182/MAX	(4183	MAX4184/MAX4185		MAX4186			MAX4187			
COMPONENT/ BW	A	v = +2V/	,	A	A _V = +1V/V		A _V = +2V/V		A _V = +1V/V			
	R _L = 1kΩ	R _L = 150Ω	R _L = 100Ω	R _L = 1kΩ	R _L = 150Ω	R _L = 100Ω	R _L = 1kΩ	R _L = 150Ω	R _L = 100Ω	R _L = 1kΩ	R _L = 150Ω	R _L = 100Ω
$R_F\left(\Omega\right)$	1k	680	620	1.5k	750	620	1.1k	7 50	680	1.6k	910	680
R _G (Ω)	1k	680	620		_	_	1.1k	750	680	_		_
-3dB BW (MHz)	245	190	160	270	205	180	245	190	175	270	205	200

Choosing Feedback and Gain Resistors

The optimum value of the external-feedback (RF) and gain-setting (RG) resistors used with the MAX4180–MAX4187 depends on the closed-loop gain and the application circuit's load. Table 1 lists the optimum resistor values for some specific gain configurations. One-percent resistor values are preferred to maintain consistency over a wide range of production lots. Figures 4a and 4b show the standard inverting and noninverting configurations. **Note:** The noninverting circuit gain (Figure 4) is 1 plus the magnitude of the inverting closed-loop gain. Otherwise, the two circuits are identical.

DC and Noise Errors

Several major error sources must be considered in any op amp. These apply equally to the MAX4180–MAX4187. Offset-error terms are given by the equation below. Voltage and current-noise errors are root-square summed and are therefore computed separately. In Figure 5, the total output offset voltage is determined by the following factors:

- The input offset voltage (Vos) times the closed-loop gain (1 = RF / RG).
- The positive input bias current (I_{B+}) times the source resistor (R_S) (usually 50Ω or 75Ω), plus the negative input bias current (I_{B-}) times the parallel combination of R_G and R_F. In current-feedback amplifiers, the input bias currents at the IN+ and IN- terminals do not track each other and may have opposite polarity, so there is no benefit to matching the resistance at both inputs.

The equation for the total DC error at the output is:

$$V_{OUT} = \left[\left(I_{B+} \right) R_S + \left(I_{B-} \right) \left(R_F \mid I \mid R_G \right) + V_{OS} \right] \left(1 + \frac{R_F}{R_G} \right)$$

The total output-referred noise voltage is:

$$e_{n(OUT)} = \left(1 + \frac{R_F}{R_G}\right) \sqrt{\left[\left(i_{n+}\right)R_S\right]^2 + \left[\left(i_{n-}\right)R_F \parallel R_G\right]^2 + \left(e_n\right)^2}$$

The MAX4180-MAX4187 have a very low, $2nV/\sqrt{Hz}$ noise voltage. The current noise at the positive input (i_{n+}) is $4pA/\sqrt{Hz}$, and the current noise at the inverting input is $5pA/\sqrt{Hz}$.

An example of the DC error calculations, using the MAX4180 typical data and typical operating circuit where R_F = R_G = $1.2k\Omega$ (R_F || R_G = 600Ω) and R_S = 37.5Ω , gives the following:

$$V_{OUT} = \left[\left(1 \times 10^{-6} \right) \times 37.5 + \left(2 \times 10^{-6} \right) \times \left(600 \right) + 1.5 \times 10^{-3} \right] \times \left(1 + 1 \right)$$

$$V_{OUT} = 4.1 \text{mV}$$

Calculating the total output noise in a similar manner yields:

$$e_{n(OUT)} = (1+1) \sqrt{4 \times 10^{-12} \times 37.5)^{2} + (5 \times 10^{-12} \times 255)^{2}}$$

$$e_{n(OUT)} = 4.8 \text{nV} / \sqrt{\text{Hz}}$$

With a 200MHz system bandwidth, this calculates to $102\mu V_{RMS}$ (approximately $612\mu V_{P-P}$, choosing the six-sigma value).

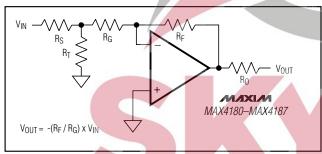


Figure 4a. Inverting Gain Configuration

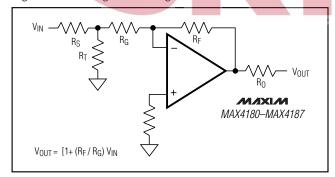


Figure 4b. Noninverting Gain Configuration

Video Line Driver

The MAX4180–MAX4187 are well suited to drive coaxial transmission lines when the cable is terminated at both ends, as shown in Figure 6. Cable-frequency response can cause variations in the signal's flatness. See Table 1 for optimum RF and RG values.

Driving Capacitive Loads

The MAX4180–MAX4187 are optimized for AC performance. They are not designed to drive highly capacitive loads. Reactive loads decrease phase margin and may produce excessive ringing and oscillation. Figure 7a shows a circuit that eliminates this problem. Placing the small (usually 5Ω to 22Ω) isolation resistor, Rs, before the reactive load prevents ringing and oscillation. At higher capacitive loads, the interaction of the load capacitance and isolation resistor controls AC performance. Figures 7b and 7c show the MAX4180 and MAX4181 frequency response with a 47pF capaci-

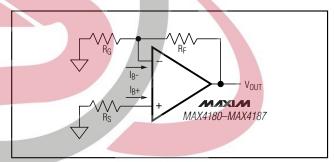


Figure 5. Output Offset Voltage

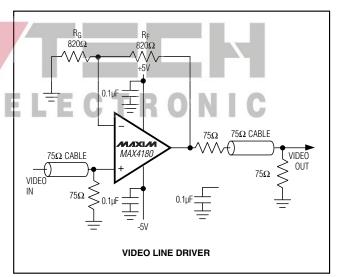


Figure 6. Video Line Driver

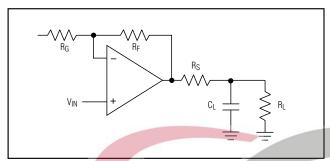


Figure 7a. Using an Isolation Resistor (Rs) for High-Capacitive Loads

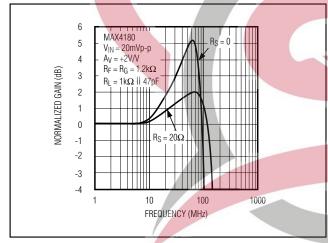


Figure 7b. Frequency Response with Capacitive Load (With and Without Isolation Resistor)

tive load. Note that in each case, gain peaking is substantially reduced when the 20Ω resistor is used to isolate the capacitive load from the amplifier output.

AC Testing/Performance

AC specifications on high-speed amplifiers are usually guaranteed without 100% production testing. Since these high-speed devices are sensitive to external parasitics introduced when automatic handling equipment is used, it is impractical to guarantee AC parameters through volume production testing. These parasitics are greatly reduced when using the recommended PC board layout (like the Maxim EV kit). Characterizing the part in this way more accurately represents the amplifier's true AC performance. Some manufacturers guarantee AC specifications without clearly stating how this guarantee is made. The AC specifications of the MAX4180-MAX4187 are derived through worst-case design simulations combined with a sample characterization of 100 units. The AC performance distributions along with the worst-case simulation results for MAX4180 and MAX4181 are shown in Figures 8-11. These distributions are repeatable provided that the proper board layout and power-supply bypassing are used (see Layout and Power-Supply Bypassing section).

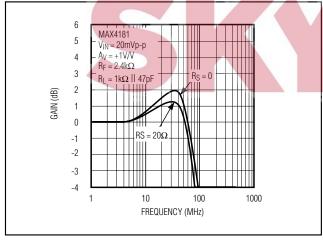


Figure 7c. Frequency Response with Capacitive Load (With and Without Isolation Resistor)



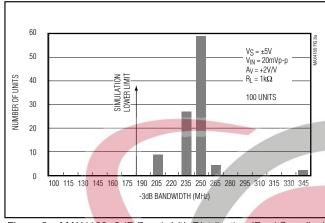


Figure 8a. MAX4180 -3dB Bandwidth Distribution (Dual Supplies)

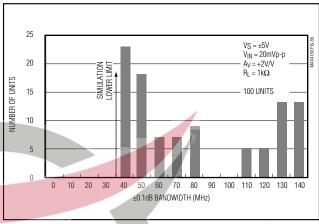


Figure 8b. MAX4180 ±0.1dB Bandwidth Distribution (Dual Supplies)

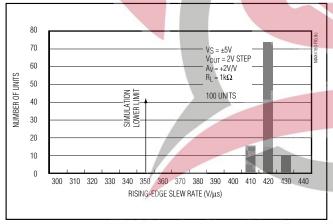


Figure 8c. MAX4180 Rising-Edge Slew-Rate Distribution (Dual Supplies)

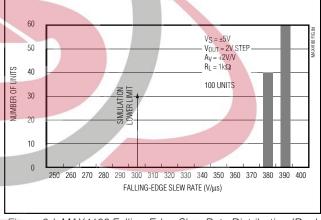


Figure 8d. MAX4180 Falling-Edge Slew-Rate Distribution (Dual Supplies)

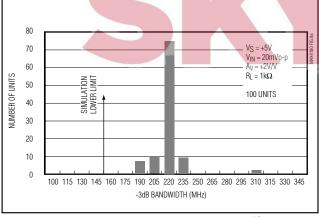


Figure 9a. MAX4180 -3dB Bandwidth Distribution (Single Supply)

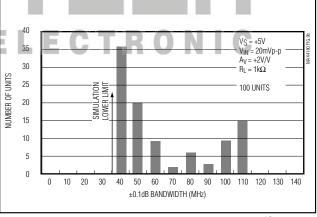


Figure 9b. MAX4180 ±0.1dB Bandwidth Distribution (Single Supply)

20 _______/N/X//

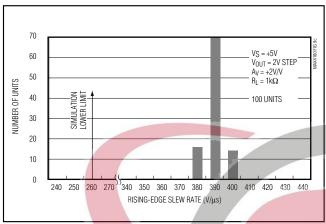


Figure 9c. MAX4180 Rising-Edge Slew-Rate Distribution (Single Supply)

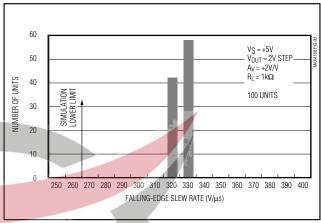


Figure 9d. MAX4180 Falling-Edge Slew-Rate Distribution (Single Supply)

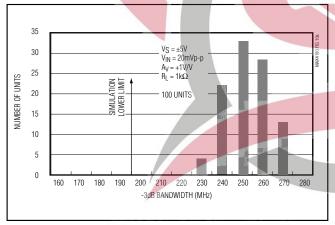


Figure 10a. MAX4181 -3dB Bandwidth Distribution (Dual Supplies)

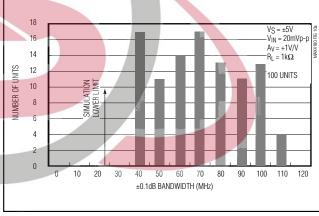


Figure 10b. MAX4181 ±0.1dB Bandwidth Distribution (Dual Supplies)

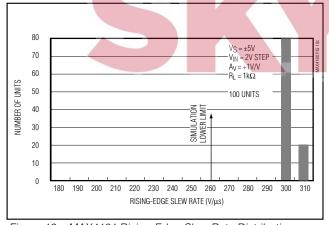


Figure 10c. MAX4181 Rising-Edge Slew-Rate Distribution (Dual Supplies)

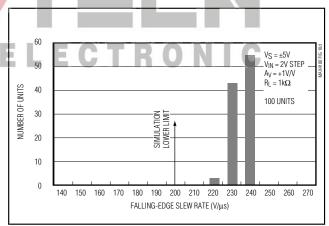


Figure 10d. MAX4181 Falling-Edge Slew-Rate Distribution (Dual Supplies)

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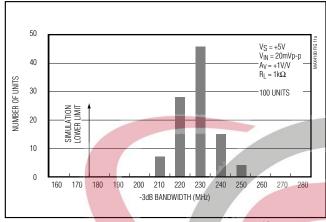


Figure 11a. MAX4181 -3dB Bandwidth Distribution (Single Supply)

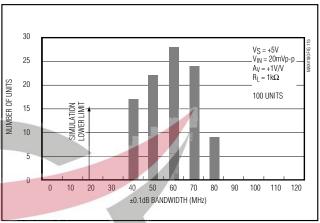


Figure 11b. MAX4181 ±0.1dB Bandwidth Distribution (Single Supply)

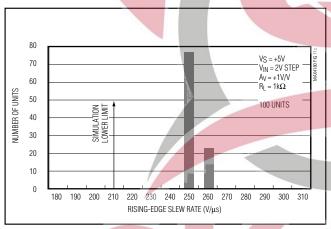


Figure 11c. MAX4181 Rising-Edge Slew-Rate Distribution (Single Supply)

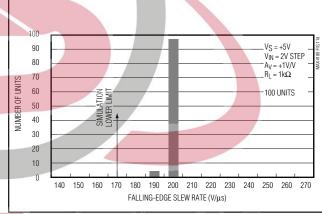
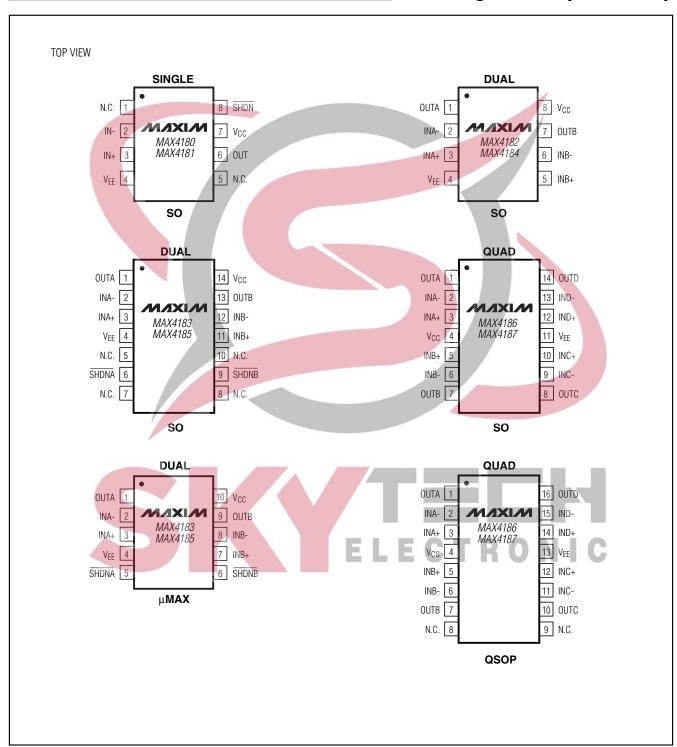


Figure 11d. MAX4181 Falling-Edge Slew-Rate Distribution (Single Supply)

ELECTRONIC

Pin Configurations (continued)



MIXIM

Ordering Information (continued)

PART	TEMP RANGE	PIN- PACKAGE	TOP MARK
MAX4181EUT-T	-40°C to +85°C	6 SOT23-6	AAAC
MAX4181ESA	-40°C to +85°C	8 SO	_
MAX4182ESA	-40°C to +85°C	8 SO	_
MAX4183EUB	-40°C to +85°C	10 μMAX*	_
MAX4183ESD	-40°C to +85°C	14 SO	_
MAX4184ESA	-40°C to +85°C	8 SO	-
MAX4185EUB	-40°C to +85°C	10 μMAX*	_
MAX4185ESD	-40°C to +85°C	14 SO	
MAX4186ESD	-40°C to +85°C	14 SO	_
MAX4186EEE	-40°C to +85°C	16 QSOP	
MAX4187ESD	-40°C to +85°C	14 SO	
MAX4187EEE	-40°C to +85°C	16 QSOP	<u> </u>

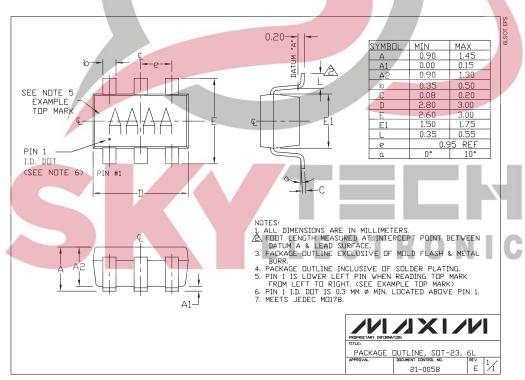
Chip Information

MAX4180/MAX4181 TRANSISTOR COUNT: 83 SUBSTRATE CONNECTED TO VEE

MAX4182-MAX4185 TRANSISTOR COUNT: 166 SUBSTRATE CONNECTED TO VEE

MAX4186/MAX4187 TRANSISTOR COUNT: 235 SUBSTRATE CONNECTED TO VEE

Package Information



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